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# Autonomous Operation of Advanced Reactors – Initial Discussions on Technical and Market Advancements

INL/MIS-25-87788 Rev:000

Battelle Energy Alliance manages INL for the  
U.S. Department of Energy's Office of Nuclear Energy



Idaho National Laboratory

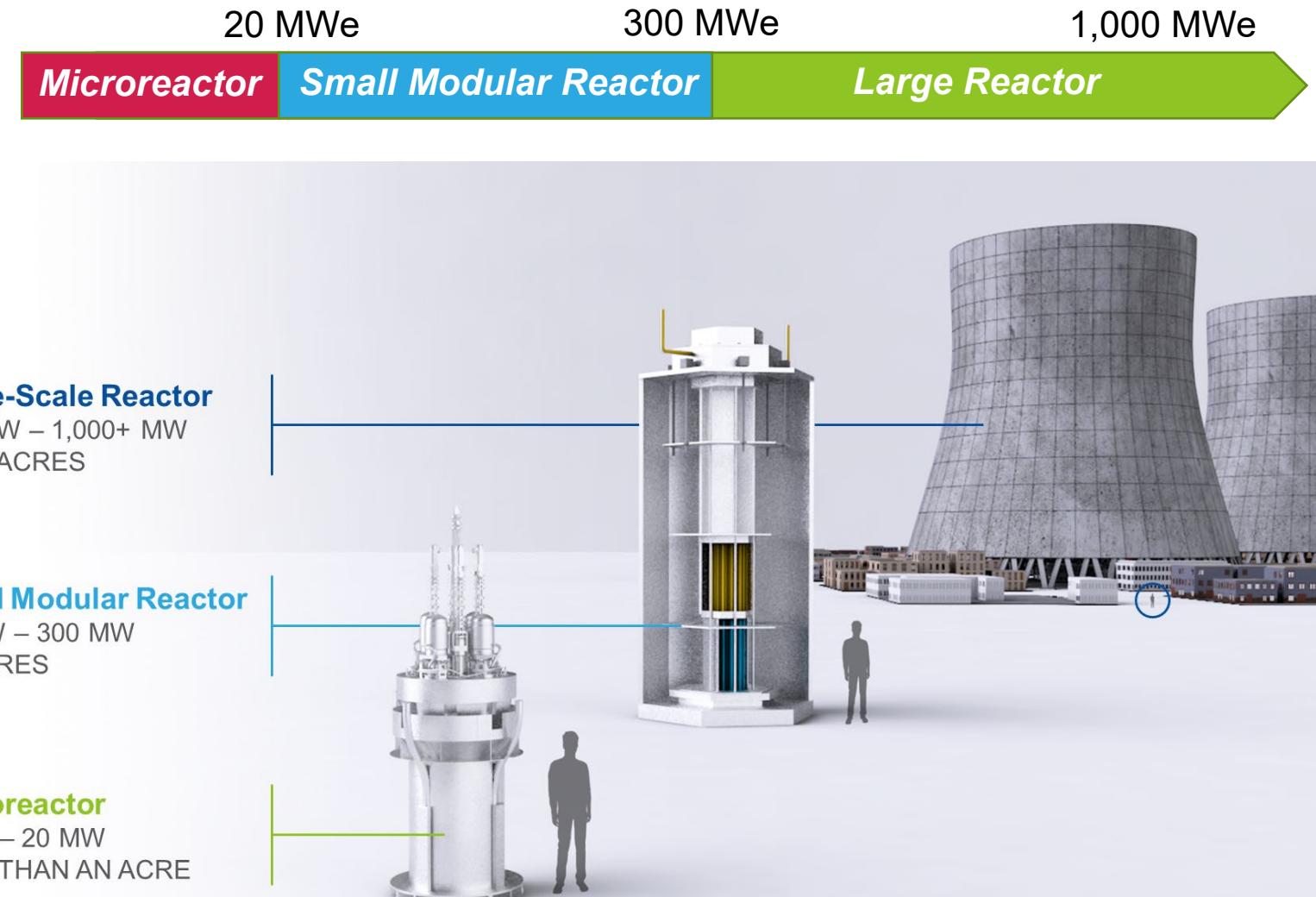
# Next Generation Reactors: Multiple Sizes and Different Levels of Autonomy

## Small Modular Reactors (SMRs)

- Smaller power output and footprint
- Modular fabrication and assembly
- Passive safety

## Microreactors

- Transportable and very easy to install
- Cater to remote communities
- Simplified safety (low source term)
- Little to no on-site staff
- Nuclear as a 'product' rather than 'project'

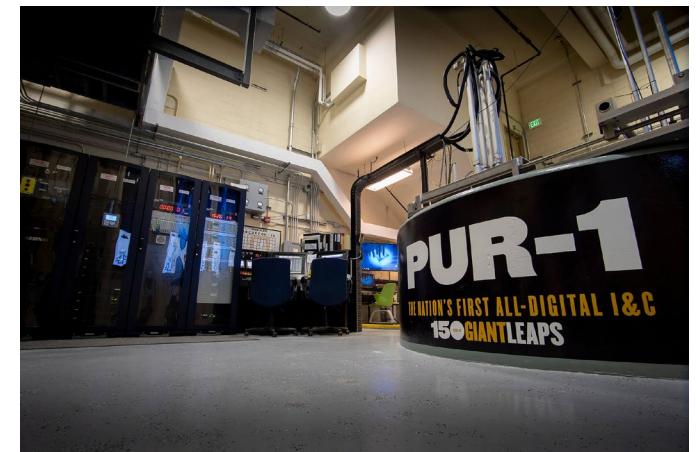


# Team

- Idaho National Laboratory
  - Vivek Agarwal
  - Linyu Lin
  - Joseph Oncken
  - Shannon Eggers
- Purdue University
  - Stylianos Chatzidakis
  - Zachery Dahm
- Curtiss-Wright (in-kind collaborator)
  - Robert England



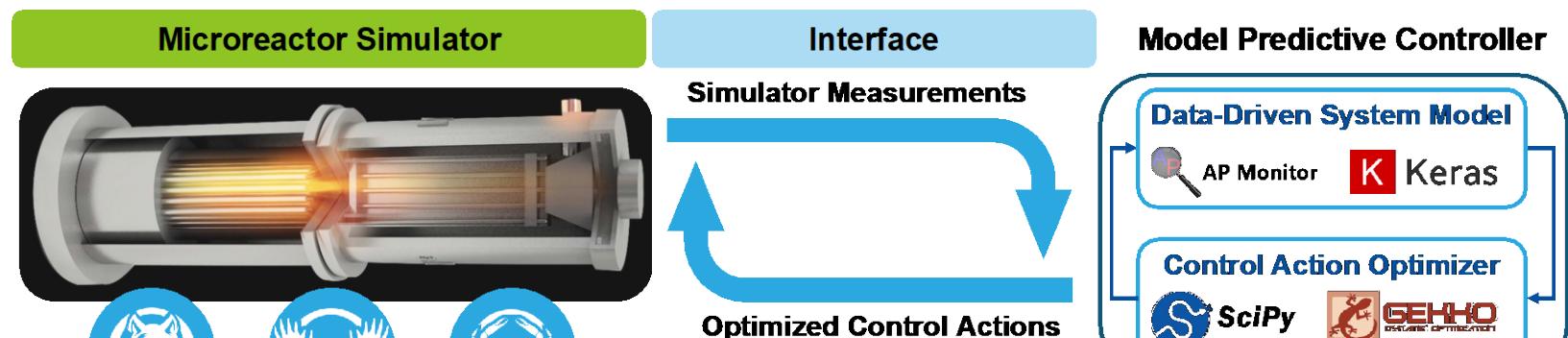
INL High Performance Computing



Purdue University Reactor One (PUR-1)

# Scalable Hybrid Modeling with Anticipatory Control Strategy for Autonomous Operation of Modular and Microreactor

- First-of-a-kind anticipatory controller **Autonomous Control fOr Reactor technology (ACORN)** to achieve autonomous control of microreactors
- Leverages and expands INL's modeling and simulation capabilities like DireWolf and BlueCRAB for capturing microreactor thermal and neutronic performance
- ACORN controller provides optimal control actions for microreactor under different scenarios and external uncertainties
  - Steady state and transient operations
  - Flexible operation (load following)
  - Failure or degraded operation



ACORN advances the level of automation to address the self-regulating attribute of microreactors. This advancement also accounts for economics of operation of microreactors.

# Project Objectives

- To advance the adoption readiness level (2 to 5) and technology readiness level (3-6) of ACORN.
- Achieve hardware-in-the-loop demonstration with PUR-1 digital control system by taking into consideration cybersecurity concerns.
- Development of user-centric visualization for situational awareness of PUR-1 with autonomous operation ability.
- Develop a training program at Purdue University for effective human machine interactions.

Seeking stakeholders' input on  
the autonomous concept of  
operations of advanced reactors



***The survey will close on October 3, 2025.***

# Autonomous Control for Reactor Technologies

*A Technology Commercialization Fund Project*



Are you thinking about Automation?  
How about Full Autonomy? How about AI for Full Autonomy?

**We want your input**

Please scan the QR code for a short survey to inform our research.  
*All feedback will be presented in aggregate, high-level form. No personally identifiable information (PII) or specific organizational data will be disclosed.*

For project details, contact: Vivek Agarwal, Distinguished Staff Scientist • Idaho National Laboratory • [vivek.agarwal@inl.gov](mailto:vivek.agarwal@inl.gov)

**In Collaboration with**



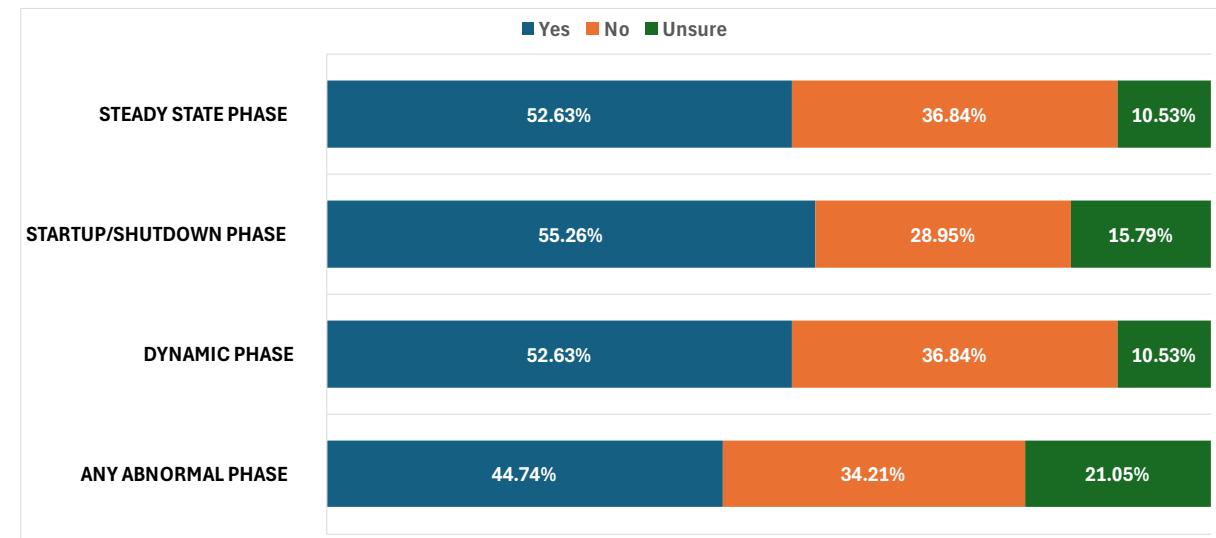
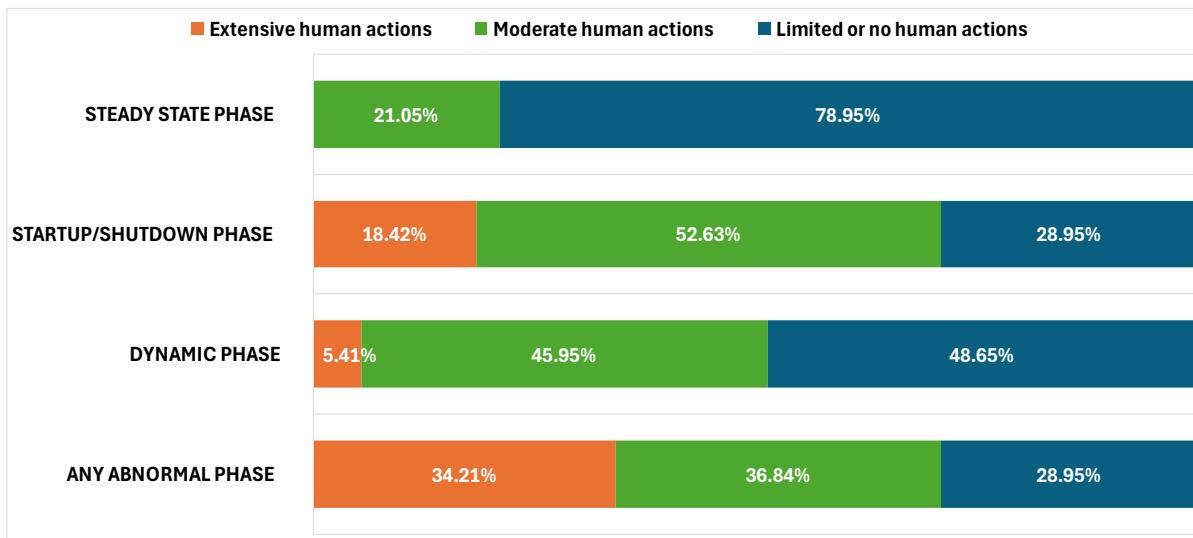
# Preliminary feedback from stakeholders

Select your concept of operations (ConOps) for the various phases of operations.

- Steady state
- Startup/Shutdown phase
- Dynamic phase
- Any abnormal phase

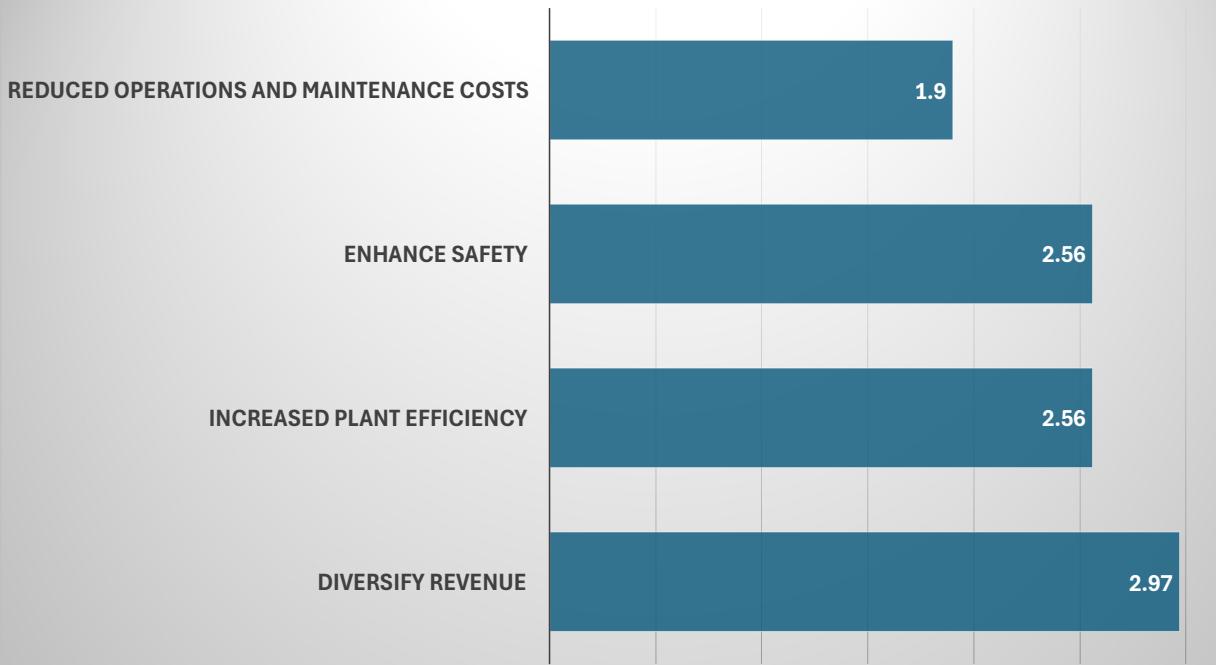
Select whether you expect your ConOps to change over time as you deploy more reactors.

- Steady state
- Startup/Shutdown phase
- Dynamic phase
- Any abnormal phase

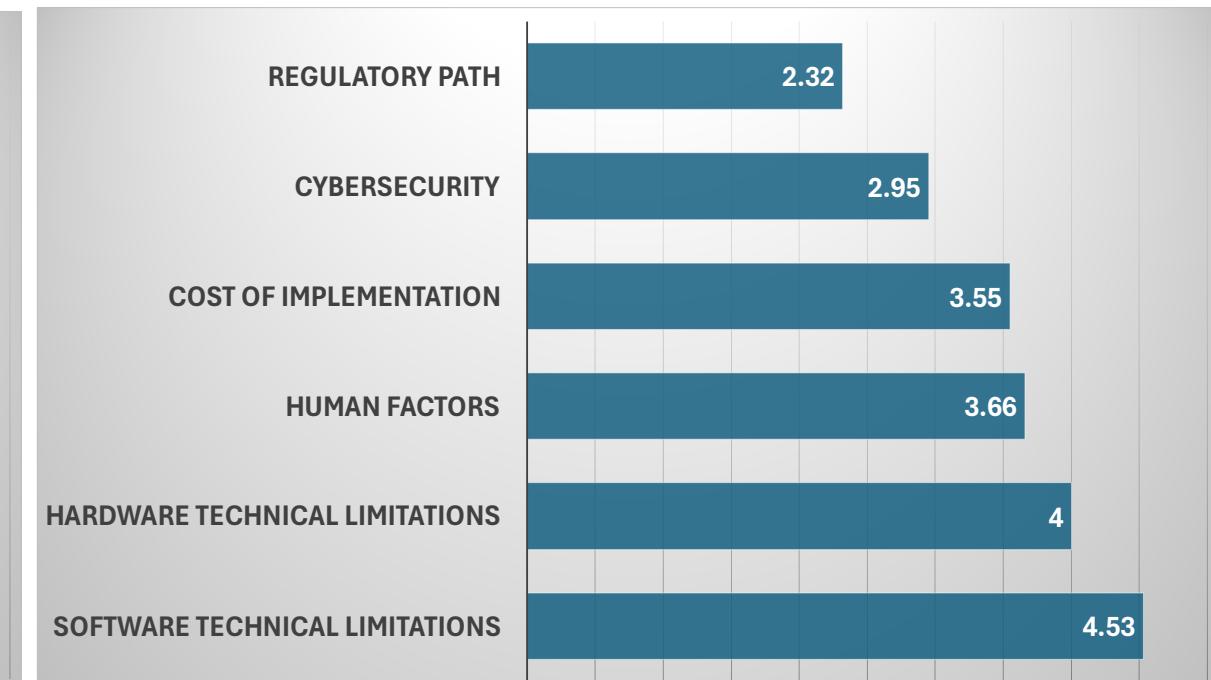


# Preliminary feedback from stakeholders

Ranked benefits of using automated or autonomous operation  
(Scale: 1-4 | 1=Biggest Benefit)

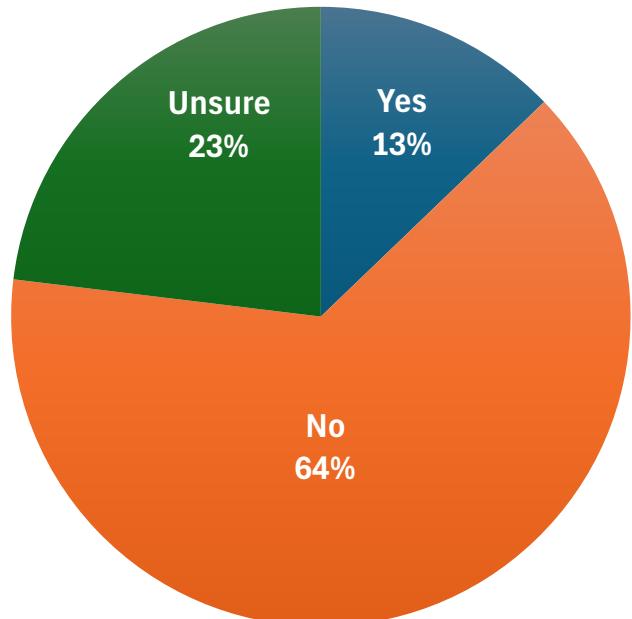


Ranked challenges with automated operation and/or autonomous control  
(Scale: 1-6 | 1=Biggest Challenge)

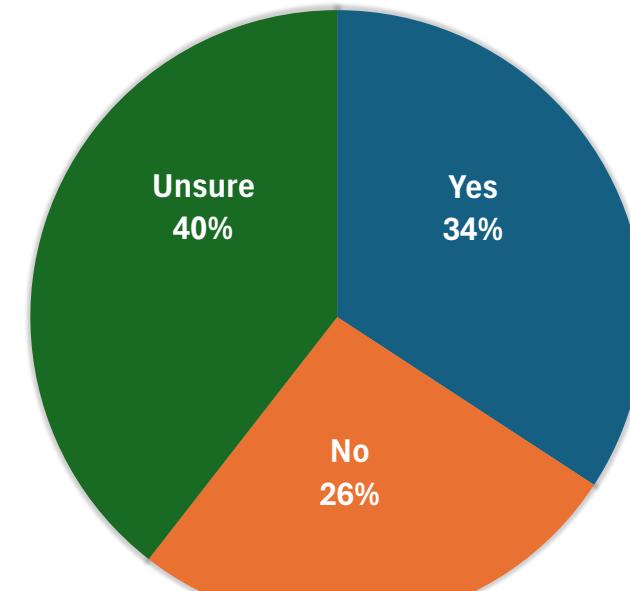


# Preliminary feedback from stakeholders

Is artificial intelligence necessary to achieve autonomous control?

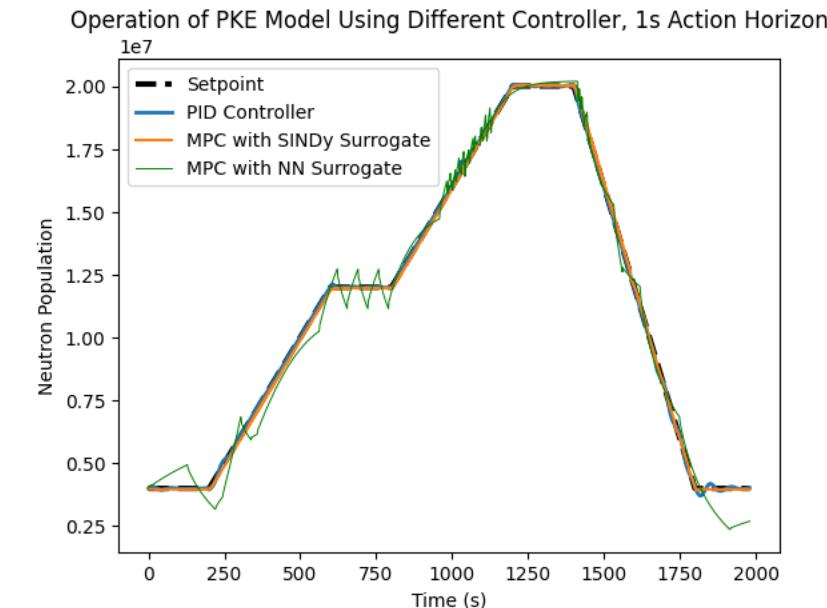
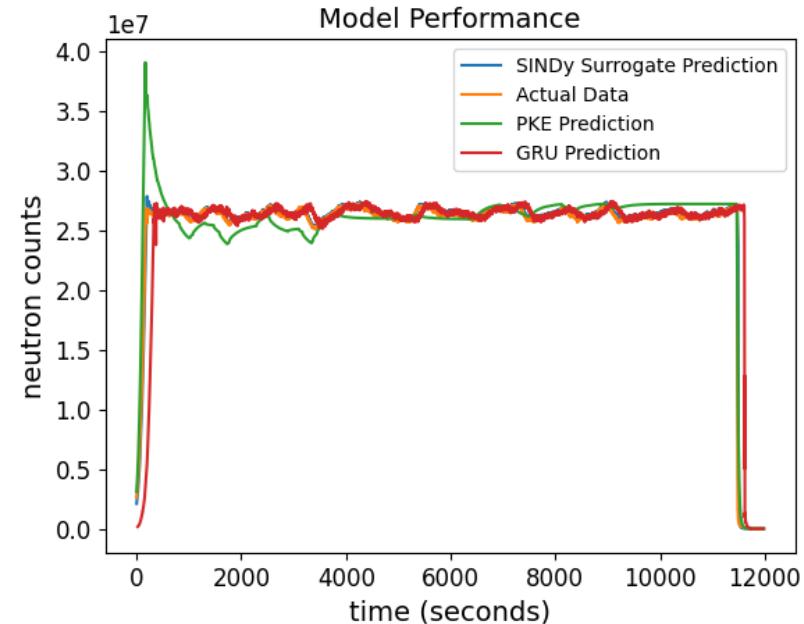


Are you comfortable with artificial intelligence being a part of an autonomous control system of a nuclear plant?



# Ongoing Research

- Adapt ACORN to PUR-1 using operational data
- Test ACORN using physics-based models, i.e., Point Kinetic (PKE) model with 6 delayed neutron groups and power feedback
- Predictors using sparse identification of nonlinear dynamics (SINDy) and neural networks
- Optimizers using line search and quadratic programming
- Control rod positions are converted to reactivity using experimentally determined rod worth curves
- Controller will adjust either:
  - Reactivity
  - Control rod positions
- Data in model and operational data is generated at 1Hz.



# Effect of action frequency on performance and stability

- MPC is better suited for slow transient with longer horizons
  - When frequent actions are needed (every second), PID performs better
  - When slow transients and less movements are preferred, MPC performs better.
- Neural network models has comparable performance when coupled with simple line search.

	Tracking Error in Mean Squared Error		
Action Horizon	MPC with SINDy	PID	MPC with Neural Network
1	0.000108	<b>0.000033</b>	0.000612
5	0.000120	<b>0.000052</b>	2.090680
10	<b>0.000144</b>	0.000480	0.001281
20	<b>0.000637</b>	0.000976	0.000948

	Number of Actions Taken			
Action Horizon	MPC with SINDy	PID	MPC with Neural Network	
1	<b>18</b>	177	565	
5	<b>36</b>	110	54	
10	<b>30</b>	45	244	
20	<b>17</b>	24	132	

## Summary and Path Forward

- The industry feedback on autonomous concept of operation of advanced reactors was presented and discussed.
- PKE model of PUR-1 with 6 delayed neutron groups and power feedback was developed.
- Different control algorithms using PUR-1 operational data and PKE model was developed and optimized using different optimization routines.
- In the budget period 2, **scenarios for PUR-1 testing will be developed and initial testing of ACORN on PUR-1 digital control system.**
- A graphic user interface will be developed for human-in-the-loop evaluation.



# Idaho National Laboratory

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